

Electric Drives and Controls

Hydraulics

Linear Motion and Assembly Technologies

Pneumatics

Service

Rexroth Bosch Group

RE 29115/08.13

Replaces: 10.05

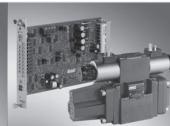
4/2, 4/3, and 5/2, 5/3 proportional directional valve, pilot operated, without electrical position feedback without/with integrated electronics (OBE)

Type .WRZ..., .WRZE... and .WRH...

Sizes 10 to 52 Component series 7X Maximum operating pressure 350 bar Maximum flow 2800 l/min



Type 4WRZE 10 ...-7X/...K31/... with integrated electronics (OBE)



1/28

Type 4WRZ 10 ...-7X/...K4/... with the corresponding control electronics (separate order)

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Features

- Pilot operated, 2-stage proportional directional valve with integrated electronics (OBE) with type 4WRZE
- Control of flow direction and size
- Operation by means of proportional solenoids with central thread and detachable coil
- For subplate mounting:

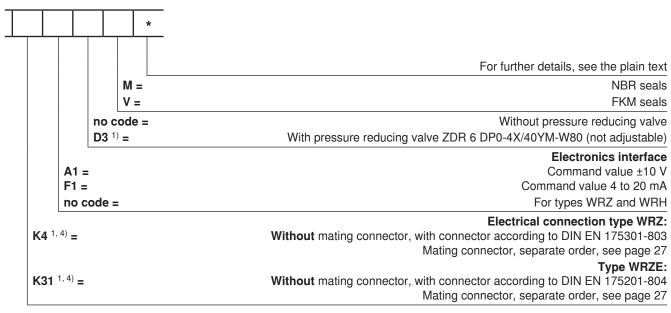
Porting pattern according to ISO 4401

- Manual override, optional
- Spring-centered control spool
- Control electronics
 - Type .WRZE...
 - Integrated electronics (OBE) with voltage or current input (A1 and/or F1)
 - Type .WRZ...
 - Digital or analog amplifier in Euro-card format
 - Analog amplifier in modular design

Information on available spare parts: www.boschrexroth.com/spc

Ordering codes (types 4WRZ and 4WRH; sizes 10 to 32 subplate mounting; size 52 flange connection)

	434/1	<u> </u>		1 1		<u></u>	- 		$\overline{}$		_
	4WI	K_		\perp	<u>-</u> 7	<u> </u>	_4_		Ш,	Щ,	Щ,
Hydraulic actuation Electro-hydraulic actuation	= H = Z										
•	= 2										
Type WRZ: For external electronics	- no	code									
With integrated electronics	_ 110	= E									
Size 10			= 10								
Size 16			= 16								
Size 25			= 25								
Size 32			= 32								
Size 52			= 52								
For control spool symbols , see page 3											
Rated flow in I/min at valve pressure differential Δp) = 10 ba	ar									
Size 10											
25 l/min				= 25							
50 l/min 85 l/min				= 50 = 85							
Size 16				= 00	'						
100 l/min				= 100)						
125 l/min				= 125							
150 l/min				= 150							
180 l/min				= 180)						
Size 25											
220 l/min				= 220)						
325 l/min				= 325	5						
Size 32											
360 l/min				= 360							
520 l/min				= 520)						
Size 52 1000 l/min				= 1000							
				= 1000							
Component series 70 to 79 (70 to 79: Unchanged installation and connection di	mensior	ns)			= 7X						
For subplate mounting					= no	code					
For flange connection (size 52 only)						= F					
Pilot control valve size 6							'				
Proportional solenoid with detachable coil						=	6E 1)				
Supply voltage											
Direct voltage 24 V							= G2	24 ¹⁾			
Without manual override							=	no c			
With concealed manual override								= N9	1, 2)		
Without special type of protection								=	no c	ode	
Seawater-resistant									=	: J ³⁾	
Pilot oil supply and return										<u> </u>	
External pilot oil supply, external pilot oil return									=	no co	
Internal pilot oil supply, external pilot oil return											= E
Internal pilot oil supply, internal pilot oil return											ET
External pilot oil supply, internal pilot oil return (only possible without code for size 52 and type 4W	BH)										= T
Corny possible without code for size 32 and type 440	1111)										

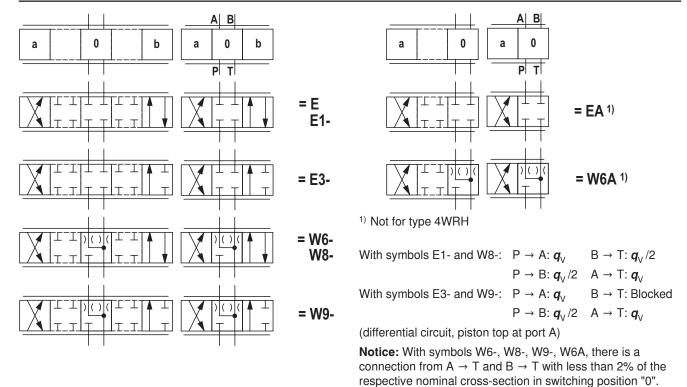


¹⁾ Not applicable with types 4WRH

- ³⁾ For information on the seawater-resistant version, see data sheet 29115-M
- ⁴⁾ For version "J" = seawater-resistant **only** "K31"

Electric special types of protection available on request.

Control spool symbols



²⁾ For version "J"→"N" instead of "N9"

Ordering codes (types 4WRZ 52 and 4WRH 52; subplate mounting)

	5W	R_	52	2	1000 +	7X/			\top	\top	\top	\top	
						_ / _	Τ'						
Hydraulic actuation Electro-hydraulic actuation	= H = Z												
Type WRZ: For external electronics With integrated electronics	= no	code = E											
Size 52			= 52										
For control spool symbols	see p	age 5											
Rated flow in I/min at valve pressure differential $\Delta p = 10$ 1000 I/min	bar			= 10	00								
Component series 70 to 79 (70 to 79: Unchanged install	ation a	nd conr	nection	dimensio	= 7X								
Pilot control valve size 6						_							
Proportional solenoid with de	tachal	ole coil			=	= 6E 1)							
Supply voltage													
Direct voltage 24 V						= (G24 1)						
Without manual override							= no						
With concealed manual ove	ride						= N	9 1, 2)					
Without special type of prote	ection							= no c					
Seawater-resistant						,			: J ³⁾				
Electrical connection type Without mating connector, we Mating connector, separate of Type WRZE: Without mating connector, we	vith cor order, s	see pag	je 27						= K	4 ^{1, 4}			
Mating connector, separate				allig to Di	IN LIN 175	201-00) 4		= 143				
Electronics interface Command value ±10 V Command value 4 to 20 mA For types WRZ and WRH											= A1 = F1		
Without pressure reducing v	alve										= no (code	
With pressure reducing valv		6 DP0-	4X/40	YM-W80	not adiust	able)				•		D3 ¹⁾	
NBR seals												-	= M
FKM seals													= V
For further details, see the p	ain tex	άt			,								

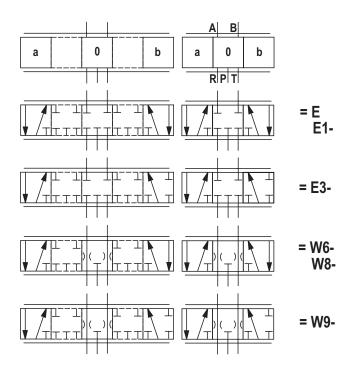
¹⁾ Not applicable with types 4WRH

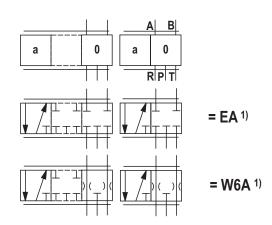
Electric special types of protection available on request.

³⁾ For information on the seawater-resistant version, see data sheet 29115-M

⁴⁾ For version "J" = seawater-resistant **only** "K31"

Control spool symbols





1) Not for type 4WRH

With symbols E1- and W8-: $P \rightarrow A$: \mathbf{q}_V $B \rightarrow T$: $\mathbf{q}_V/2$

 $P \rightarrow B: \boldsymbol{q}_V/2 \quad A \rightarrow R: \boldsymbol{q}_V$

With symbols E3- and W9-: $P \rightarrow A$: \mathbf{q}_V $B \rightarrow T$: Blocked

 $P \rightarrow B: q_V/2 \quad A \rightarrow R: q_V$

(differential circuit, piston top at port A)

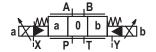
Notice:

- Only external pilot oil supply and return possible
- With control spool W6-, W8-, W9-, W6A, there is a connection from A \rightarrow R and B \rightarrow T with less than 2% of the respective nominal cross-section in switching position "0".

Symbols (simplified)

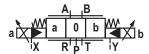
With electro-hydraulic actuation and for external electronics

Type 4WRZ...-7X./... and type 4WRZ 52...-7XF/...



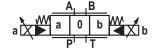
X = externalY = external

Type 5WRZ 52-7X./...

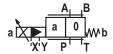


X = externalY = external

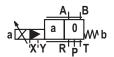
Type 4WRZ...-7X./...ET...



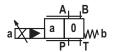
X = internal Y = internal Type 4WRZ...A-7X./... and type 4WRZ 52 A...-7XF/...



Type 5WRZ 52 A-7X./...

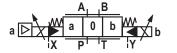


Type 4WRZ.A...-7X./...ET...



With electro-hydraulic actuation and for integrated electronics

Type 4WRZE...-7X./... and type 4WRZE 52...-7XF/...



X = external

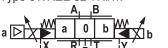
Y = external

X = external

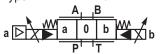
Y = external

X = internalY = internal

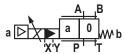
Type 5WRZE 52-7X./...



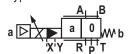
Type 4WRZE...-7X./...ET...



Type 4WRZE...A-7X./... and type 4WRZE 52 A...-7XF/...



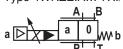
Type 5WRZE 52 A-7X./...



Type 4WRZE.A...-7X./...ET...

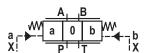
Type 4WRH...A...-7X./... and

type 4WRH 52...-7XF/...

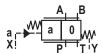


With hydraulic actuation

Type 4WRH...-7X./... and type 4WRH 52...-7XF/...

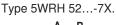


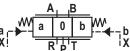
X = external Y = external



Type 5WRH 52 A...-7X./...







X = externalY = external

Pilot control valve type 3DREP 6...

The pilot control valve is a 3-way pressure reducing valve that is actuated by a proportional solenoid. It converts an electrical input signal into a proportional pressure output signal and is used for all valves of the type 4WRZ... and 5WRZ...

The proportional solenoids are controllable, wet-pin DC solenoids with a central thread and a detachable coil. The solenoids are controlled by external electronics (type .WRZ...).

Set-up:

The valve basically consists of:

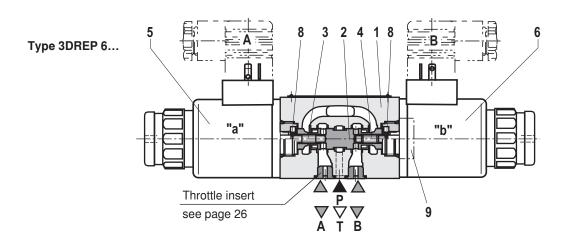
- Housing (1)
- Control spool (2) with pressure measuring spool (3 and 4)
- Solenoids (5 and 6) with central threads

Function:

The pressure in A or B is set by means of the proportional solenoids. The amount of the pressure depends on the current. With de-energized solenoids (5, 6), the control spool (2) is held in the central position by means of the pressure springs (8). Ports A and B are connected with T so that the hydraulic fluid can flow to the tank without obstructions.

By energizing a proportional solenoid, e.g. solenoid "a" (5), the pressure measuring spool (3) and with it the control spool (2) are moved to the right. This opens the connection from P to B and A to T via orifice-type cross-sections with progressive flow characteristic. With the surface of the pressure measuring spool (4) the pressure that builds up in channel B acts on the control spool and against the solenoid force. The pressure measuring spool (4) is supported by solenoid "b". If the pressure exceeds the value set at solenoid "a", the control spool (2) is pushed back against the solenoid force and connects B with T until the set pressure is reached again. The pressure is proportional to the solenoid current. When the solenoid is switched off, the control spool (2)

When the solenoid is switched off, the control spool (2) is returned into the central position by the compression springs (8).



Pilot control valve with two switching positions (type 3DREP 6...B...)

The operation of this valve version basically corresponds to the valve with 3 switching positions. However, this 2 spool position valve is only equipped with solenoid "a" (5). In the place of the second proportional solenoid there is a plug screw (9).

Information on type 3DREP 6:

Prevent the tank line from draining. If this is possible due to installation conditions, install a preload valve (with a preload pressure of approx. 2 bar).

Pilot control valve type 3DREPE 6...

The pilot control valve is a 3-way pressure reducing valve that is actuated by a proportional solenoid. It converts an electrical input signal into a proportional pressure output signal and is used for all valves of the type 4WRZE... and 5WRZE...

The proportional solenoids are controllable, wet-pin DC solenoids with a central thread and a detachable coil. The solenoids are controlled by the integrated electronics (type .WRZE...).

Set-up:

The valve basically consists of:

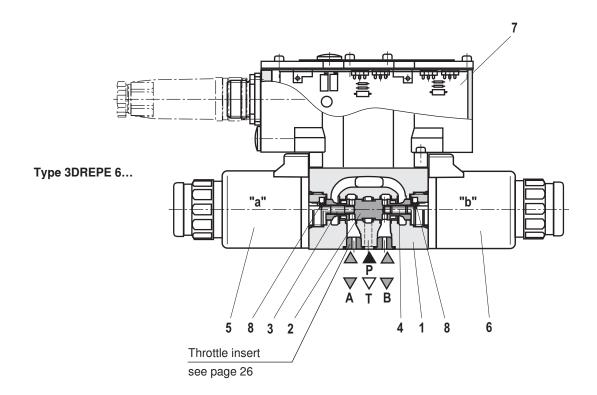
- Housing (1)
- Control spool (2) with pressure measuring spool (3 and 4)
- Solenoids (5 and 6) with central threads
- Integrated electronics (7)

Function:

The pressure in A or B is set by means of the proportional solenoids. The amount of the pressure depends on the current. With de-energized solenoids (5, 6), the control spool (2) is held in the central position by means of the pressure springs (8). Ports A and B are connected with T so that the hydraulic fluid can flow to the tank without obstructions.

By energizing a proportional solenoid, e.g. solenoid "a" (5), the pressure measuring spool (3) and with it the control spool (2) are moved to the right. This opens the connection from P to B and A to T via orifice-type cross-sections with progressive flow characteristic. With the surface of the pressure measuring spool (4) the pressure that builds up in channel B acts on the control spool and against the solenoid force. The pressure measuring spool (4) is supported by solenoid "b". If the pressure exceeds the value set at solenoid "a", the control spool (2) is pushed back against the solenoid force and connects B with T until the set pressure is reached again. The pressure is proportional to the solenoid current.

When the solenoid is switched off, the control spool (2) is returned into the central position by the compression springs (8).



Pilot operated proportional directional valves Types 4WRZ... and 5WRZ.52...

Valves of type 4WRZ... are pilot operated 4-way directional valves that are actuated by proportional solenoids. They control the flow direction and size.

Valves of type 5WRZ... are equipped with an additional port "R" (only size 52).

Set-up:

The valve basically consists of:

- Pilot control valve (9) with proportional solenoids (5 and 6)
- Main valve (10) with main control spool (11) and centering spring (12)

M Notice!

Due to the design principle, internal leakage is inherent to the valves, which may increase over the life cycle.

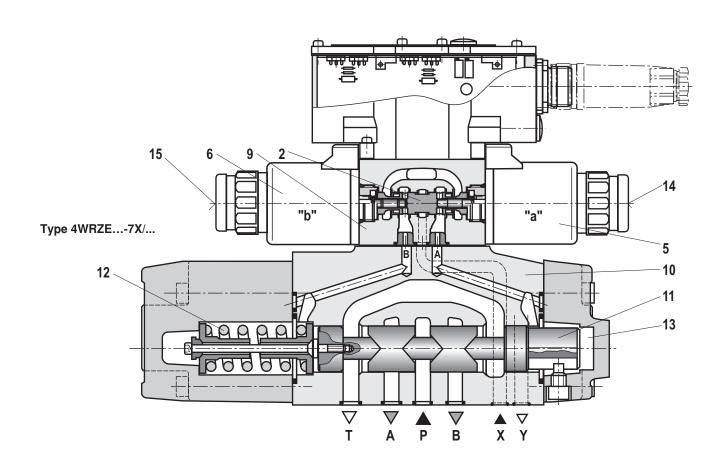
Function:

- With de-energized solenoids (5, 6), the main control spool (11) is held in the central position by means of the centering spring (12).
- The main control spool (11) is controlled by the pilot control valve (9); the main control spool is proportionally moved, e.g. by actuating solenoid "b" (6).
 - → The control spool (2) is moved to the right, pilot oil enters the pressure chamber (13) via the pilot control valve (9) and deflects the main control spool (11) according to the electric input signal.
 - → This opens the connection from P to B and A to T via orifice-type cross-sections with progressive flow characteristic.
- Pilot oil is internally supplied to the pilot control valve via port P or externally via port X.
- Switching the solenoid off (6)
 - → The control spool (2) and main control spool (11) are moved back into the central position.
- Depending on the switching position, flow occurs from P to A and B to T or P to B and A to T (R).

An optional manual override (14 and 15) can be used to move the control spool (2) without solenoid energization.

Motice:

Inadvertent activation of the manual override may result in uncontrollable machine movements.



Externally pilot operated proportional directional valves Types 4WRH... and 5WRH.52...

Valves of the type .WRH... are pilot operated proportional directional valves for external actuation via pressure control valves.

Set-up:

The valve basically consists of:

- Main valve (10) with main control spool (11) and centering spring (12)
- Diversion plate (16)

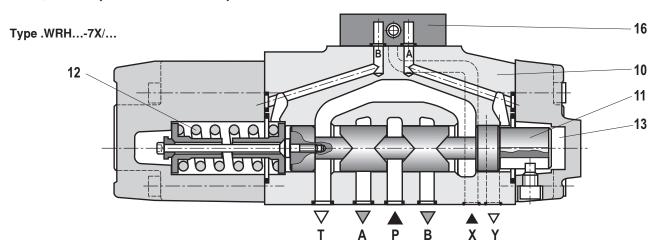
Motice!

Due to the design principle, internal leakage is inherent to the valves, which may increase over the life cycle.

Function

- The diversion plate (16) connects control port A that leads to the pressure chamber (13) with port Y and control port B with port X.
- If port X is pressurized, the main control spool (11) is moved to the right (P to B and A to T). If port Y is pressurized, the main control spool is moved to the left (P to A and B to T).

The pilot pressure at the main valve must not exceed 25 bar (16 bar with size 52)!



Technical data (for applications outside these parameters, please consult us!)

Valve type				.WRZ	.WRZE	.WRH	
Installation position			Any, preferably horizontal				
			(for commissioni	ng information, see da	ata sheet 07800)		
Storage tem	perature range		°C	-20 to +80			
Ambient ten	nperature range		°C	–20 to +70	-20 to +50	-20 to +70	
Weight	 Subplate mounting 	Size 10	kg	7.8	8.0	6.1	
		Size 16	kg	11.9	12.1	9.7	
		Size 25	kg	18.2	18.4	18.0	
		Size 32	kg	42.2	42.2	41.5	
		Size 52	kg	79.5	79.7		
	- Flange connection	Size 52	kg	77.5	77.7		
	- With "D3"		kg	+0.5 in addition			
Sine test acc	cording to DIN EN 60068-2-	6:2008	10 cycles, 10200010 Hz with logarithmic frequency changing speed of 1 oct./min., 5 to 57 Hz, amplitude 1.5 mm (p-p), 57 to 2000 Hz, amplitude 10 g, 3 axes				
Random test according to DIN EN 60068-2-64:2009				202000 Hz, amplitude 0.05 g ² /Hz (10 g _{RMS}) 3 axes, 30 min testing time per axis			
Shock test a	according to DIN EN 60068-	2-27:2010	Half sine 15 g/11 ms, 3 times in positive/3 times in negative direction per axis, 3 axes				
				Variant 2 +25 °C to +55 °C, 9 2 cycles at 24 hours	90% to 97% relative h	umidity,	

Technical data (for applications outside these parameters, please consult us!)

hydraulic (measured with HLP46, $\vartheta_{oil} = 40 \text{ °C} \pm 5 \text{ °C}$ and p = 100 bar) Size 25 32 52 Operating pressure - Pilot control valve External pilot oil supply 30 to 100 bar 20 to 100 Internal pilot oil supply 100 to bar 315 only 100 to 350 only with "D3" with "D3" bar Main valve Up to 315 Up to 350 Up to 350 Up to 350 Up to 350 Return flow pressure - Port T (port R) Up to 315 Up to 250 Up to 250 Up to 150 Up to 250 bar (external pilot oil return) - Port T bar Up to 30 Up to 30 Up to 30 Up to 30 (internal pilot oil return) Port Y bar Up to 30 Flow of the main valve I/min Up to 170 Up to 460 Up to 870 Up to 1600 Up to 2800 Pilot flow at ports X and Y I/min 3.5 5.5 7 15.9 7 with stepped input signal 0 → 100% Pilot volume cm³ 1.7 4.6 10 26.5 54.3 for switching process 0 → 100% Hvdraulic fluid See table below Hydraulic fluid temperature range -20 to +80 (preferably +40 to +50) (at the valve working ports) Viscosity range mm²/s 20 to 380 (preferably 30 to 46) Maximum admissible degree of contamination of the hydraulic fluid, cleanliness class according to ISO 4406 (c) - Pilot control valve Class 18/16/13 1) Class 20/18/15 1) - Main valve % ≤ 6 Hysteresis

¹⁾ The cleanliness classes specified for the components must be adhered to in hydraulic systems. Effective filtration prevents faults and at the same time increases the life cycle of the components.
For the selection of the filters, see www.boschrexroth.com/filter

Hydraulic fluid		Classification	Suitable sealing materials	Standards
Mineral oils and relat	ed hydrocarbons	HL, HLP	NBR, FKM	DIN 51524
Flame-resistant	containing water	HFC (Fuchs HYDROTHERM 46M, Petrofer Ultra Safe 620)	NBR	ISO 12922

Important information on hydraulic fluids!

- For more information and data on the use of other hydraulic fluids refer to data sheet 90220 or contact us!
- There may be limitations regarding the technical valve data (temperature, pressure range, life cycle, maintenance intervals, etc.)!
- The flash point of the process and operating medium used must be 40 K greater than the maximum solenoid surface temperature.
- Flame-resistant containing water: The maximum pressure differential per control edge is 175 bar. Pressure preloading at the tank port > 20% of the pressure differential; otherwise, increased cavitation.
- Life cycle as compared to operation with mineral oil HL, HLP 50% to 100%

VT-HACD-1-1X/... according to data sheet 30143

VT-SWKA-1-1X/... according to data sheet 30255

1.8

3

±10

4 to 20

Technical data (for applications outside these parameters, please consult us!)

electric						
Valve type				.WRZ ¹⁾ .WRZE		
Voltage type				Direct voltage		
Command value overlap %				15		
Maximum current			Α	1.5	2.5	
Solenoid coil resistance – Cold value at 20 °C		Ω	4.8	2		
		- Maximum hot value	Ω	7.2	3	
Duty cycle			%	100		
Maximum coil tempe	rature ³⁾		°C	150		
Protection class of the	ne valve ac	cording to EN 60529		IP65 with mating connectors mounted and locked		
Control electron	nics					
Type 4WRZ	Digita	l amplifier in Euro-card form	at ²⁾	VT-VSPD-1-2X/ according to data sheet 30523		
		og amplifier in Euro-card forn ramp time	nat ²⁾	VT-VSPA2-1-2X/V0/T1, according to data sheet 30110		
Analog amplifier in Euro-card format ²⁾ with 5 ramp times		nat ²⁾	VT-VSPA2-1-2X/V0/T5, according to data sheet 30110			
Analog module amplifier 2)			VT-11118-1X/ according to data sheet 30218			
Type 4WRZE				Integrated in the valve, see page 14		
	Analo	og command value module 2))	VT- SWMA-1-1X/ according	g to data sheet 29902	
	Analo	og command value module 23)	VT-SWMAK-1-1X/ according to data sheet 29903		

Α

Α

٧

 $\mathsf{m}\mathsf{A}$

Command value signal - Voltage input "A1"

Current consumption

Digital command value card ²⁾

Analog command value card 2)

- Impulse current

- Current input "F1"

¹⁾ With Bosch Rexroth AG control electronics

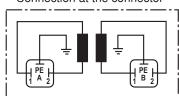
²⁾ Separate order

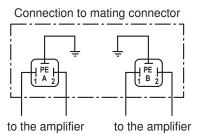
³⁾ Due to the temperatures occurring at the surfaces of the solenoid coils, the European standards ISO 13732-1 and EN 982 need to be adhered to.

Electrical connection

For type .WRZ... (for external electronics – not with version "J" = seawater-resistant)
For mating connectors, see page 27

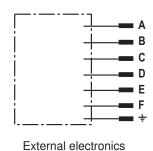
Connection at the connector





For type .WRZ... (for external electronics – with version "J" = seawater-resistant)

For mating connectors, see page 27



Contact	Connection with
Α	Solenoid A
В	Solenoid B
С	Solenoid A
D	Solenoid B
E	n.c.
F	n.c.
PE	Valve housing

For type .WRZE... (with integrated electronics (OBE) and with version "J" = seawater-resistant) For mating connectors, see page 27

Connector pin assignment	Contact	Signal with A1	Signal at F1	
Supply voltage	A	24 VDC (u (t) = 19.4	to 35 V); I _{max} = 2 A	
	В	0	V	
Reference (actual value)	С	Cannot b	pe used 1)	
Differential amplifier input	D	\pm 10 V; \mathbf{R}_{e} > 50 kΩ 4 to 20 mA; \mathbf{R}_{e}		
(Command value)	E	Command value r	eference potential	
	F	Cannot be used 1)		
Protective grounding conductor	PE	Connected to cooling element and valve housing		

¹⁾ Contacts C and F must not be connected!

Command value: A positive command value (0 to 10 V or 12 to 20 mA) at D and a reference potential at E result in a flow from P to A and B to T.

A negative command value (0 to -10 V or 12 to 4 mA) at D and a reference potential at E result in a flow from P to B and A to T.

If the valve and the solenoid are on side "a" (control spool variants EA and W6A), a positive command value at D and a reference potential at E result in flow from P to B and A to T.

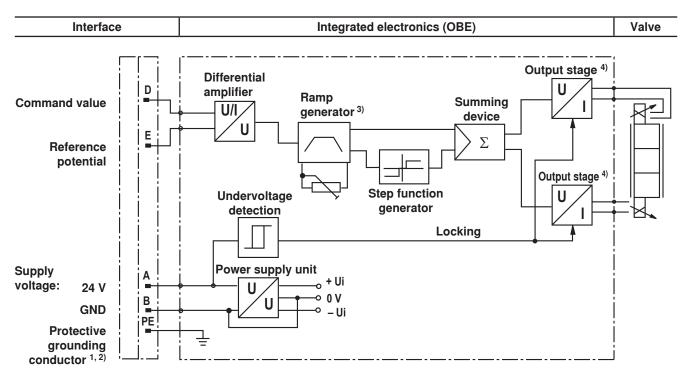
Connection cable: Recommendation: – Up to 25 m cable length, type LiYCY $5 \times 0.75 \text{ mm}^2$

- Up to 50 m 25 m cable length, type LiYCY 5 x 1.0 mm²

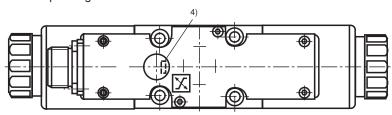
External diameter 6.5 to 11 mm

Only install the shield on the supply side on the protective grounding conductor.

Block diagram of the integrated electronics (OBE) for type WRZE

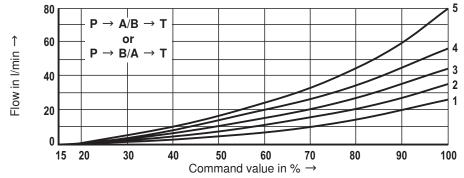


- 1) Port PE is connected to the cooling element and the valve housing
- ²⁾ The protective grounding conductor is screwed to the valve housing and cover
- $^{3)}$ Ramp can be set from 0 to 2.5 s from the outside, identical for $T_{\rm up}$ and $T_{\rm down}$
- 4) The output stages are current-controlled



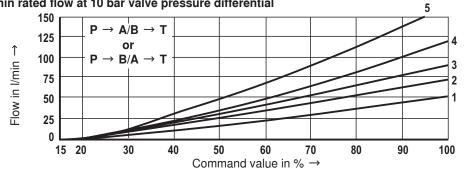
Characteristic curves size 10 (control spool "E, W6-, EA, W6A" as well as HLP46, $\vartheta_{\text{oil}} = 40 \, ^{\circ}\text{C} \pm 5 \, ^{\circ}\text{C}$ and $p = 100 \, \text{bar}$)

25 I/min rated flow at 10 bar valve pressure differential



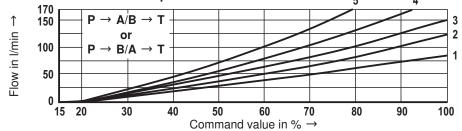
- $\Delta p = 10$ bar, constant
- $\Delta p = 20$ bar, constant
- $\Delta p = 30$ bar, constant
- $\Delta p = 50$ bar, constant
- $\Delta p = 100$ bar, constant

50 I/min rated flow at 10 bar valve pressure differential



- $\Delta p = 10$ bar, constant
- $\Delta p = 20$ bar, constant
- $\Delta p = 30$ bar, constant
- $\Delta p = 50$ bar, constant
- $\Delta p = 100$ bar, constant

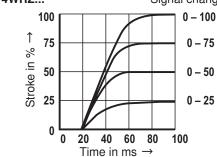
85 I/min rated flow at 10 bar valve pressure differential

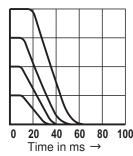


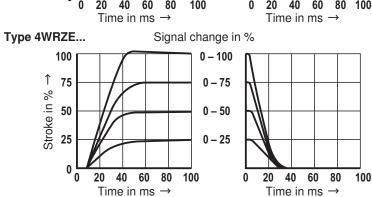
- $\Delta p = 10$ bar, constant
- $\Delta p = 20$ bar, constant
- $\Delta p = 30$ bar, constant
- $\Delta p = 50$ bar, constant
- $\Delta p = 100$ bar, constant

 Δp = valve pressure differential according to DIN 24311 (inlet pressure p_P minus load pressure p_L minus return flow pressure p_T)

Transition functions with stepped, electric input signals, measured at p_{St} = 50 bar Signal change in % Type 4WRZ...

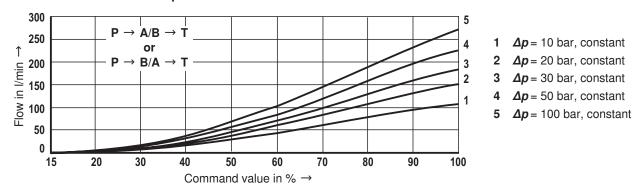




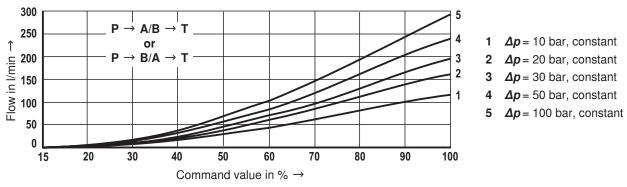


Characteristic curves size 16 (control spool "E, W6-, EA, W6A" as well as HLP46, $\vartheta_{oil} = 40 \text{ °C } \pm 5 \text{ °C}$ and p = 100 bar)

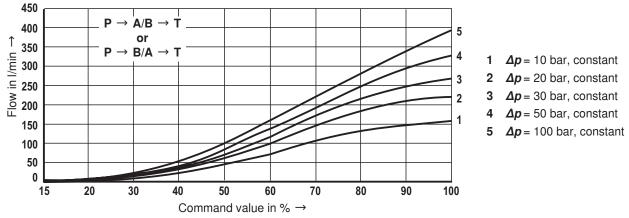
100 l/min rated flow at 10 bar valve pressure differential



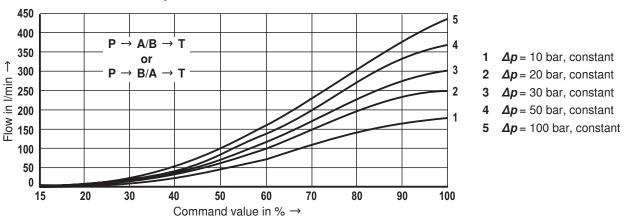
125 I/min rated flow at 10 bar valve pressure differential



150 I/min rated flow at 10 bar valve pressure differential



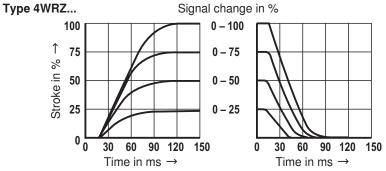
180 I/min rated flow at 10 bar valve pressure differential

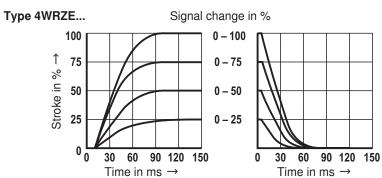


 Δp = valve pressure differential according to DIN 24311 (inlet pressure p_p minus load pressure p_t minus return flow pressure p_T)

Characteristic curves size 16 (control spool "E, W6-, EA, W6A" as well as HLP46, $\vartheta_{oil} = 40$ °C ±5 °C and p = 100 bar)

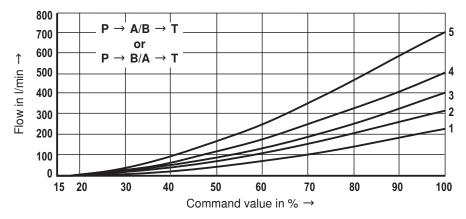
Transition functions with stepped, electric input signals, measured at p_{St} = 50 bar





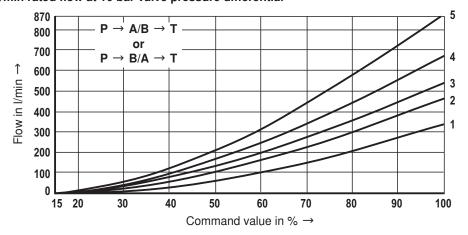
Characteristic curves size 25 (control spool "E, W6-, EA, W6A" as well as HLP46, ϑ_{oil} = 40 °C ±5 °C and p = 100 bar)

220 I/min rated flow at 10 bar valve pressure differential



- 1 $\Delta p = 10$ bar, constant
- 2 $\Delta p = 20$ bar, constant
- 3 $\Delta p = 30$ bar, constant
- 4 $\Delta p = 50$ bar, constant
- 5 $\Delta p = 100$ bar, constant

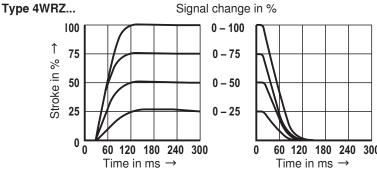
325 I/min rated flow at 10 bar valve pressure differential

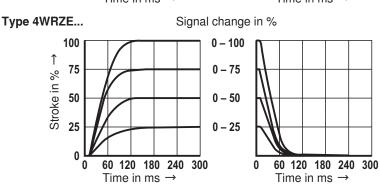


- 1 $\Delta p = 10$ bar, constant
- $\Delta p = 20$ bar, constant
- $\Delta p = 30$ bar, constant
- 4 $\Delta p = 50$ bar, constant
- $\Delta p = 100 \text{ bar, constant}$

 Δp = valve pressure differential according to DIN 24311 (inlet pressure p_P minus load pressure p_I minus return flow pressure p_T)

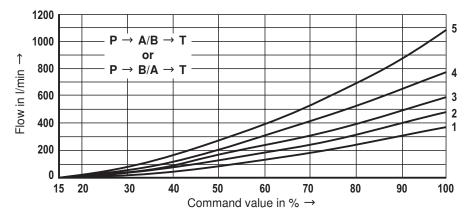
Transition functions with stepped, electric input signals, measured at $p_{\rm St}$ = 50 bar





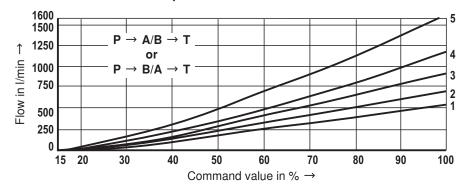
Characteristic curves size 32 (control spool "E, W6-, EA, W6A" as well as HLP46, $\vartheta_{nil} = 40$ °C ±5 °C and p = 100 bar)

360 I/min rated flow at 10 bar valve pressure differential



- $\Delta p = 10$ bar, constant
- $\Delta p = 20$ bar, constant
- $\Delta p = 30$ bar, constant
- $\Delta p = 50$ bar, constant
- $\Delta p = 100$ bar, constant

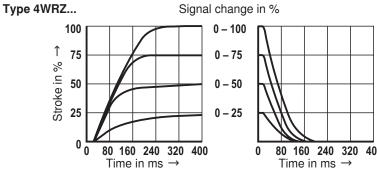
520 l/min rated flow at 10 bar valve pressure differential

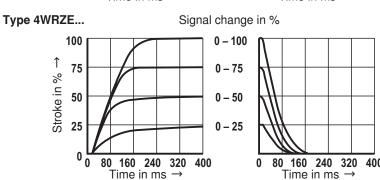


- $\Delta p = 10$ bar, constant
- $\Delta p = 20$ bar, constant
- $\Delta p = 30$ bar, constant
- $\Delta p = 50$ bar, constant
- **Δp** = 100 bar, constant

 Δp = valve pressure differential according to DIN 24311 (inlet pressure p_P minus load pressure p_T minus return flow pressure p_T)

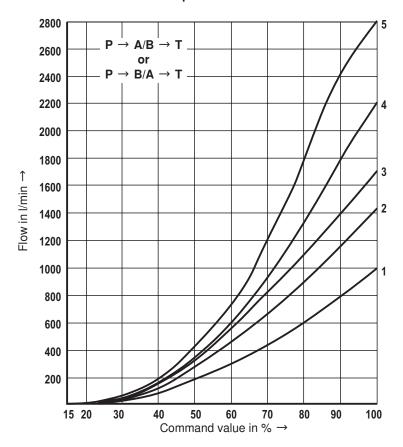
Transition functions with stepped, electric input signals, measured at p_{St} = 50 bar





Characteristic curves size 52 (control spool "E, W6-, EA, W6A" as well as HLP46, $\vartheta_{oil} = 40 \, ^{\circ}\text{C} \pm 5 \, ^{\circ}\text{C}$ and $p = 100 \, \text{bar}$)

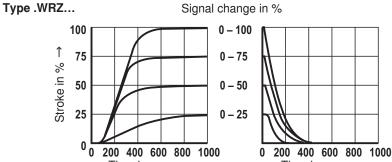
1000 I/min rated flow at 10 bar valve pressure differential

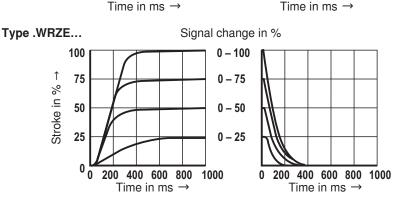


- 1 $\Delta p = 10$ bar, constant
- 2 $\Delta p = 20$ bar, constant
- 3 $\Delta p = 30$ bar, constant
- 4 $\Delta p = 50$ bar, constant
- 5 $\Delta p = 100$ bar, constant

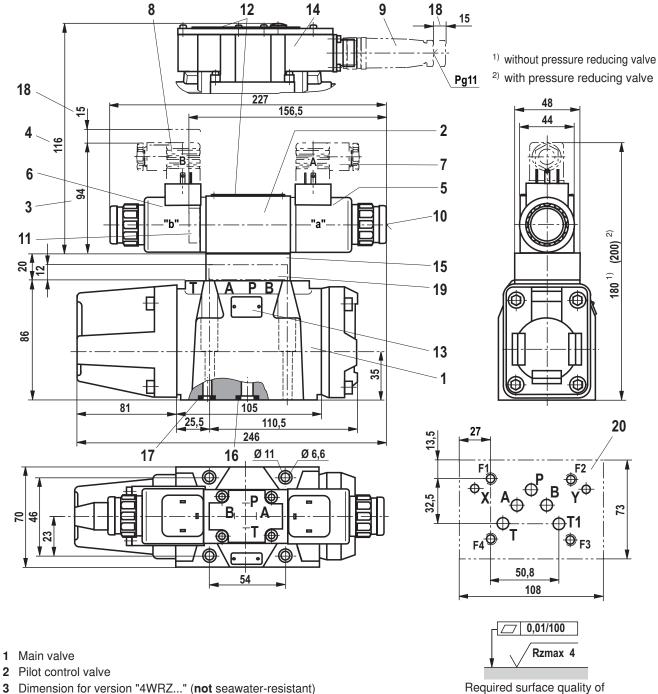
 Δp = valve pressure differential according to DIN 24311 (inlet pressure p_P minus load pressure p_I minus return flow pressure p_T)

Transition functions with stepped, electric input signals, measured at p_{St} = 50 bar





Dimensions: Size 10 (dimensions in mm)

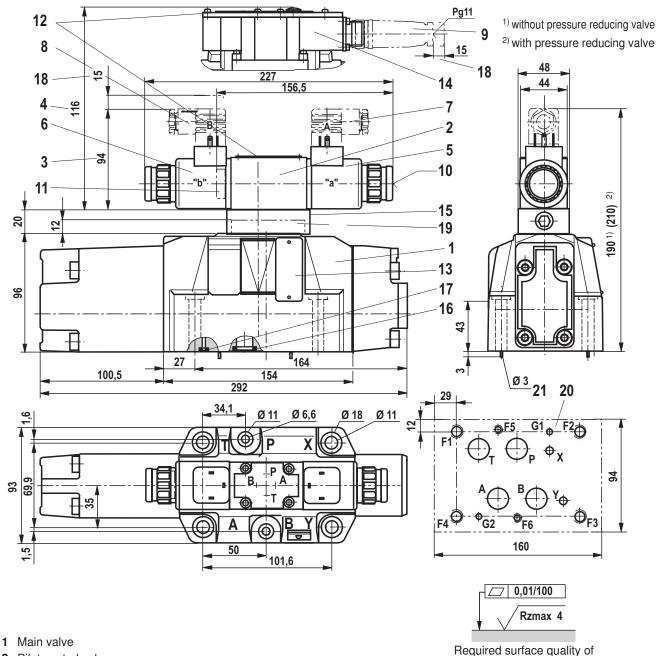


- 3 Dimension for version "4WRZ..." (not seawater-resistant)
- 4 Dimension for version "4WRZE..."
- 5 Proportional solenoid "a"
- 6 Proportional solenoid "b"
- 7 Mating connector "A", separate order, see page 27
- 8 Mating connector "B", separate order, see page 27
- 9 Mating connector, separate order, see page 27
- 10 Concealed manual override "N9"
- 11 Plug screw for valves with one solenoid
- 12 Name plate for pilot control valve
- 13 Name plate for main valve
- 14 Integrated electronics (OBE)

- 15 Pressure reducing valve "D3"
- 16 Identical seal rings for ports A, B, P, T, and T1
- 17 Identical seal rings for ports X and Y
- 18 Space required to remove the mating connector
- 19 Diversion plate (type 4WRH...)
- 20 Machined installation surface, porting pattern according to ISO 4401-05-05-0-05, ports X and Y as required

the valve contact surface

Dimensions: Size 16 (dimensions in mm)



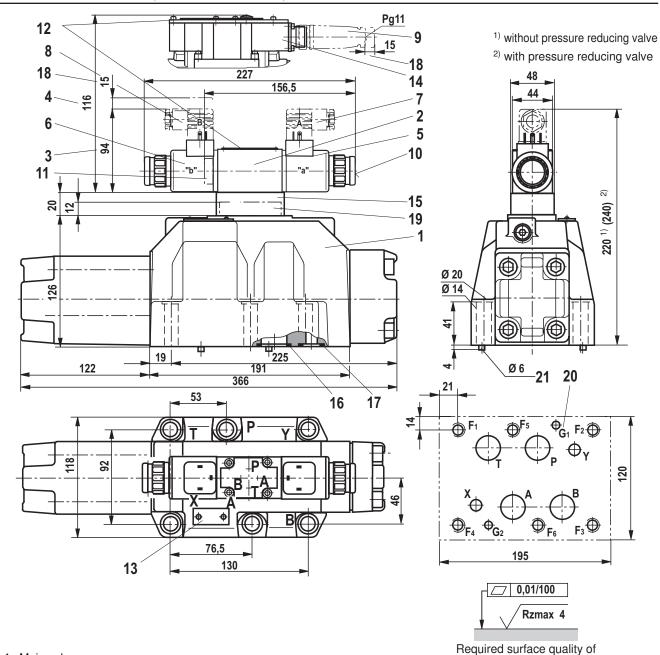
- 2 Pilot control valve
- 3 Dimension for version "4WRZ..." (not seawater-resistant)
- Dimension for version "4WRZE..."
- 5 Proportional solenoid "a"
- 6 Proportional solenoid "b"
- 7 Mating connector "A", separate order, see page 27
- 8 Mating connector "B", separate order, see page 27
- 9 Mating connector, separate order, see page 27
- 10 Concealed manual override "N9"
- 11 Plug screw for valves with one solenoid
- 12 Name plate for pilot control valve
- 13 Name plate for main valve
- 14 Integrated electronics (OBE)

- 15 Pressure reducing valve "D3"
- 16 Identical seal rings for ports A, B, P, and T
- Identical seal rings for ports X and Y
- 18 Space required to remove the mating connector
- 19 Diversion plate (type 4WRH...)
- 20 Machined installation surface, porting pattern according to ISO 4401-07-07-0-05, ports X and Y as required deviating from the standard: Ports A, B, P, T Ø20 mm.

the valve contact surface

21 Locking pin

Dimensions: Size 25 (dimensions in mm)



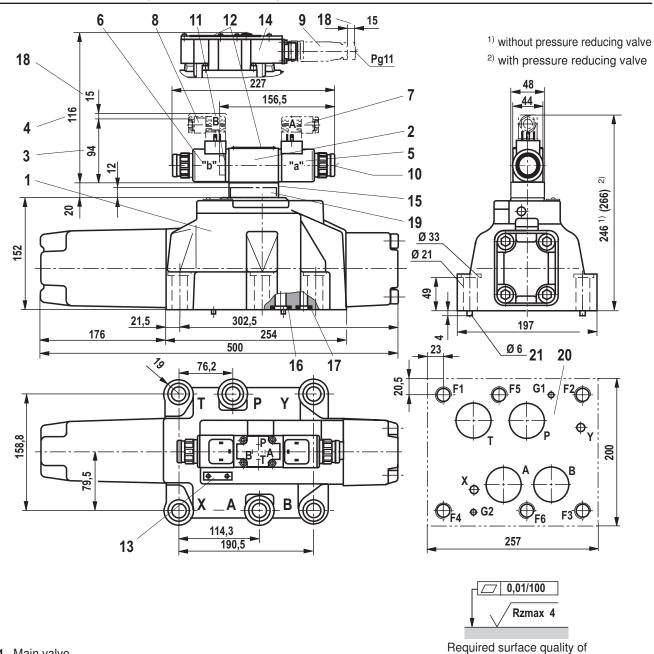
- 1 Main valve
- 2 Pilot control valve
- **3** Dimension for version "4WRZ..." (**not** seawater-resistant)
- 4 Dimension for version "4WRZE..."
- 5 Proportional solenoid "a"
- 6 Proportional solenoid "b"
- 7 Mating connector "A", separate order, see page 27
- 8 Mating connector "B", separate order, see page 27
- **9** Mating connector, separate order, see page 27
- 10 Concealed manual override "N9"
- 11 Plug screw for valves with one solenoid
- 12 Name plate for pilot control valve
- 13 Name plate for main valve
- 14 Integrated electronics (OBE)

- 15 Pressure reducing valve "D3"
- 16 Identical seal rings for ports A, B, P, and T
- 17 Identical seal rings for ports X and Y
- 18 Space required for removing the mating connector
- 19 Diversion plate (type 4WRH...)
- 20 Machined installation surface, porting pattern according to ISO 4401-08-08-0-05, ports X and Y as required

the valve contact surface

21 Locking pin

Dimensions: Size 32 (dimensions in mm)



- Main valve
- 2 Pilot control valve
- 3 Dimension for version "4WRZ..." (not seawater-resistant)
- Dimension for version "4WRZE..."
- 5 Proportional solenoid "a"
- 6 Proportional solenoid "b"
- 7 Mating connector "A", separate order, see page 27
- 8 Mating connector "B", separate order, see page 27
- 9 Mating connector, separate order, see page 27
- 10 Concealed manual override "N9"
- Plug screw for valves with one solenoid 11
- 12 Name plate for pilot control valve
- 13 Name plate for main valve
- 14 Integrated electronics (OBE)

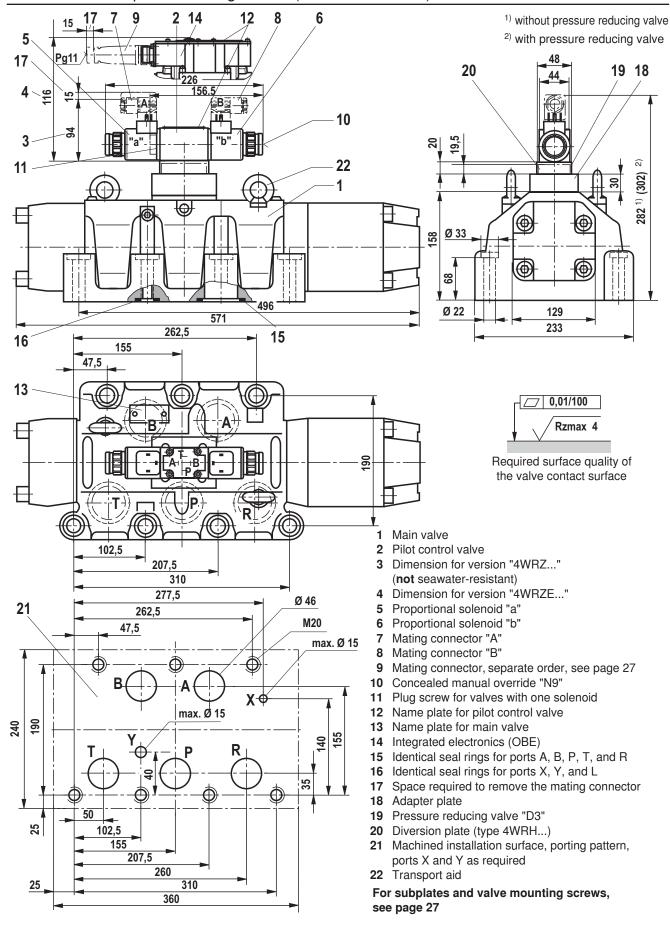
- 15 Pressure reducing valve "D3"
- 16 Identical seal rings for ports A, B, P, and T
- 17 Identical seal rings for ports X and Y
- Space required for removing the mating connector
- 19 Diversion plate (type 4WRH...)
- Machined installation surface, porting pattern according to ISO 4401-10-09-0-05, ports X and Y as required deviating from the standard:

the valve contact surface

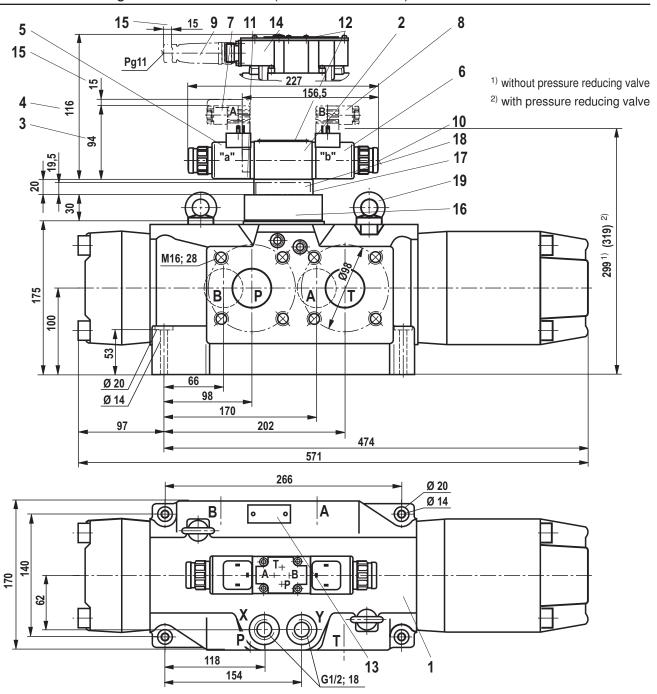
- Ports A, B, T and P Ø38 mm.
- 21 Locking pin

For subplates and valve mounting screws, see page 27

Dimensions: Subplate mounting size 52 (dimensions in mm)



Dimensions: Flange connection size 52 (dimensions in mm)



- 1 Main valve
- 2 Pilot control valve
- 3 Dimension for version "4WRZ..." (not seawater-resistant)
- 4 Dimension for version "4WRZE..."
- 5 Proportional solenoid "a"
- 6 Proportional solenoid "b"
- 7 Mating connector "A", separate order, see page 27
- 8 Mating connector "B", separate order, see page 27
- 9 Mating connector, separate order, see page 27
- 10 Concealed manual override "N9"

- 11 Plug screw for valves with one solenoid
- 12 Name plate for pilot control valve
- 13 Name plate for main valve
- 14 Integrated electronics (OBE)
- 15 Space required to remove the mating connector
- 16 Adapter plate
- 17 Pressure reducing valve "D3"
- **18** Diversion plate (type 4WRH...)
- 19 Transport aid

For subplates and valve mounting screws, see page 27

Accessories (not included in the scope of delivery)

Mating connectors			Material number
Mating connector for 4WRZ	DIN EN 175301-803	Solenoid "a", grey	R901017010
		Solenoid "b", black	R901017011
Mating connector for 4WRZE	DIN EN 175201-804		e.g. R900021267 (plastic)
and 4WRZEJ			e.g. R900223890 (metal)

Hexagon socket he	ad cap screws	Material number
Size 10	4x ISO 4762 - M6 x 45 - 10.9-flZn-240h-L Tightening torque M_A = 13.5 Nm ±10% or 4x ISO 4762 - M6 x 45 - 10.9 Tightening torque M_A = 15.5 Nm ±10%	R913000258
Size 16	2x ISO 4762 - M6 x 60 - 10.9-flZn-240h-L Tightening torque $\textit{M}_{\rm A}$ = 12.2 Nm ±10% 4x ISO 4762 - M10 x 60 - 10.9-flZn-240h-L Tightening torque $\textit{M}_{\rm A}$ = 58 Nm ±20% or 2x ISO 4762 - M6 x 60 - 10.9 Tightening torque $\textit{M}_{\rm A}$ = 15.5 Nm ±10% 4x ISO 4762 - M10 x 60 - 10.9 Tightening torque $\textit{M}_{\rm A}$ = 75 Nm ±20%	R913000115 R913000116
Size 25	6x ISO 4762 - M12 x 60 - 10.9-flZn-240h-L Tightening torque M _A = 100 Nm ±20% or 6x ISO 4762 - M12 x 60 - 10.9 Tightening torque M _A = 130 Nm ±20%	R913000121
Size 32	6x ISO 4762 - M20 x 80 - 10.9-flZn-240h-L Tightening torque M_A = 340 Nm ±20% or 6x ISO 4762 - M20 x 80 - 10.9 Tightening torque M_A = 430 Nm ±20%	R901035246
Size 52 (5WRZ52)	With a steel installation surface: $7x \text{ ISO} 4762 - \text{M2O} \times 90 - 10.9 \text{-fIZn-240h-L}$ Tightening torque $\textit{M}_{A} = 465 \text{ Nm} \pm 20\%$ With a cast iron installation surface: $7x \text{ ISO} 4762 - \text{M2O} \times 100 - 10.9 \text{-fIZn-240h-L}$ Tightening torque $\textit{M}_{A} = 465 \text{ Nm} \pm 20\%$ or With a steel installation surface: $7x \text{ ISO} 4762 - \text{M2O} \times 90 - 10.9$ Tightening torque $\textit{M}_{A} = 610 \text{ Nm} \pm 20\%$ With a cast iron installation surface: $7x \text{ ISO} 4762 - \text{M2O} \times 100 - 10.9$ Tightening torque $\textit{M}_{A} = 610 \text{ Nm} \pm 20\%$	R913000397 R913000386
Size 52 (4WRZ52)	4x ISO 4762 - M12 x 70 - 10.9-flZn-240h-L Tightening torque M_A = 100 Nm ±20% or 4x ISO 4762 - M12 x 70 - 10.9 Tightening torque M_A = 130 Nm ±20%	R913000515

Subplates/connection flanges	Data sheet
Size 10	45054
Size 16	45056
Size 25	45058
Size 32	45060
Size 52	45501

Throttle insert	Ø in mm	Material number
Size 10	1.8	R900158510
Size 16	2.0	R900158547
Size 25	2.8	R900157948
Size 32	-	-
Size 52	-	-

Notes

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